

Northern Illinois University



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Main Objective

To enable researchers and gas companies expedite the identification and repair of fugitive gas leaks, our research proposes an explainable and auditable statistical framework to perform gas-leak surveys using an Unmanned Aerial Vehicle (UAV).

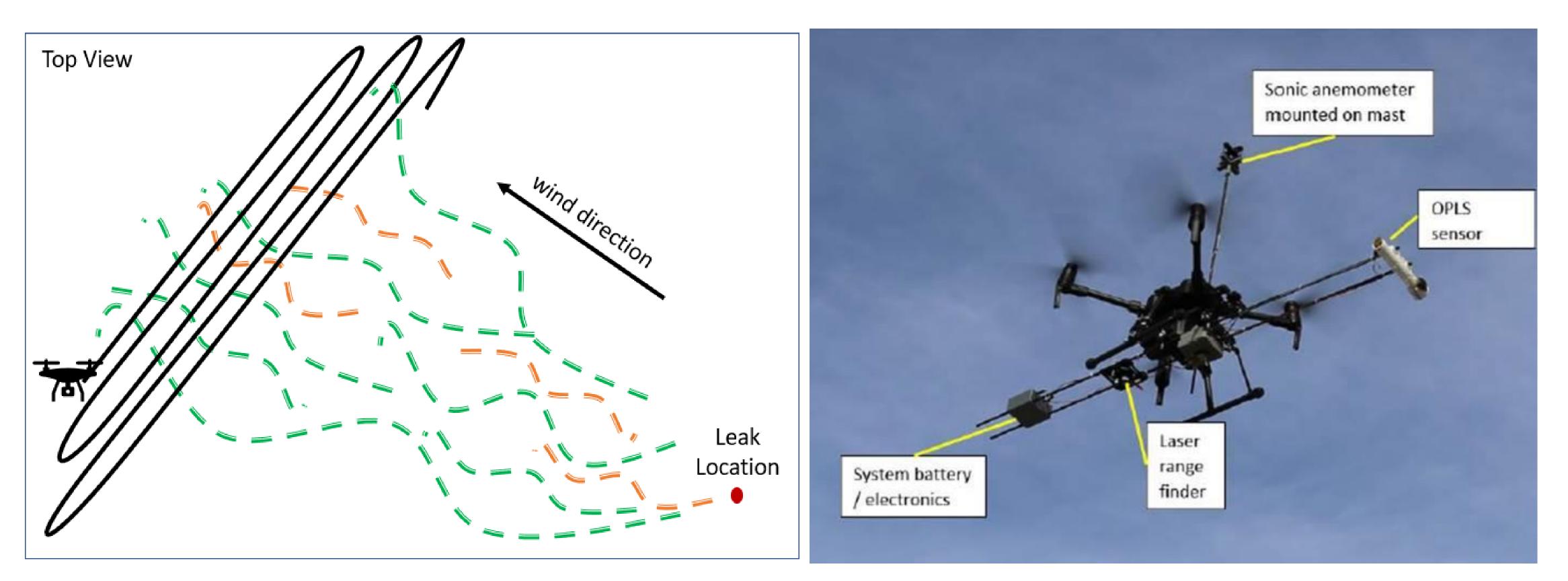


Figure 1. UAV crossing gas plume and collecting methane gas concentration measurements to produce survey map.

Project Approach/Scope

- Upwind Survey Regions (USR) mapping measure
- Information from multiple USRs fused to class
- Statistical decision framework used to produ
- Survey map indicates areas clear of gas leaks
- Survey map indicates areas requiring further

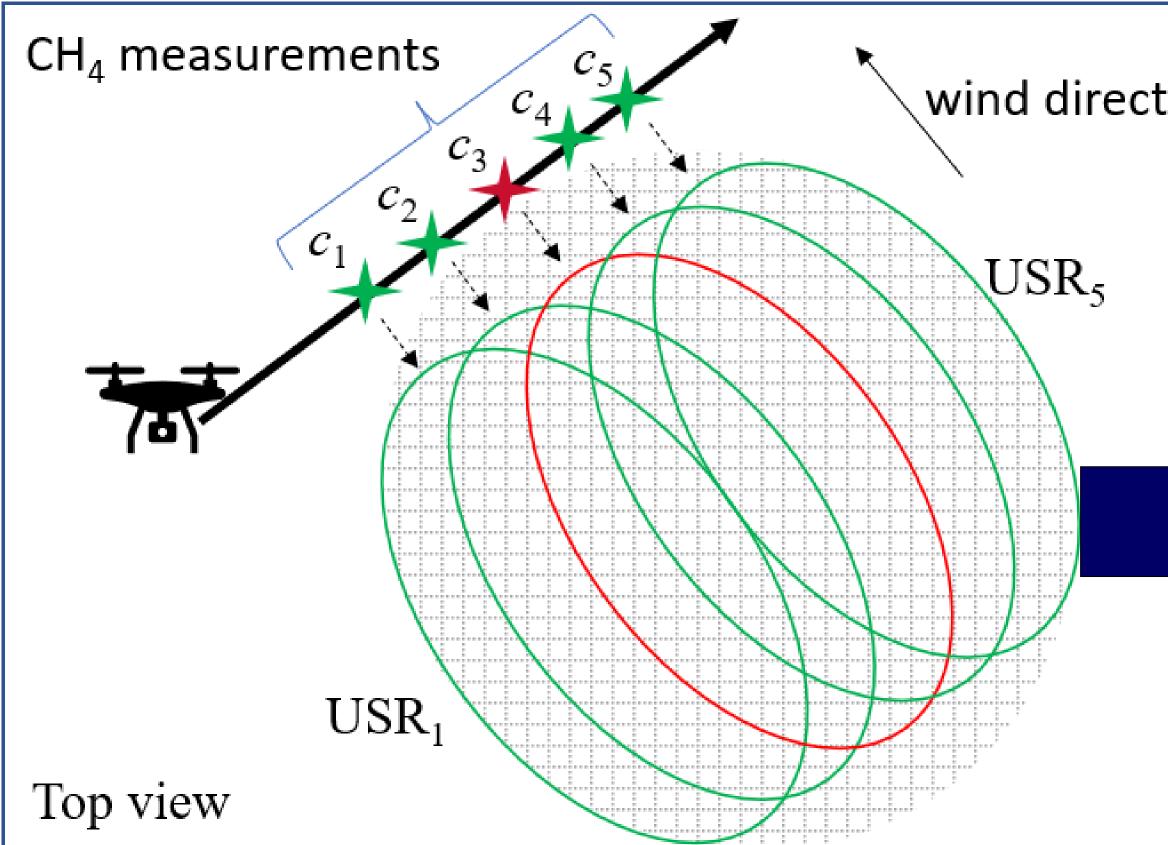


Figure 3. USRs from low concentration measureme USRs from high concentration measurements providi Multiple USRs cover each grid point. Fusion procedure produces survey map.

An Auditable Framework for Fugitive Gas Leak Surveys using an Unmanned Aerial Vehicle

Figure 2. UAV and OPLS sensor used in experiments

| asurer | nents into regions on the ground. | 140 |
|---------------------------------------------------|---------------------------------------------|-----------------|
| assify each grid point. | | |
| uce Survey Map. | | 120 |
| ks witł | n a certain reliability. | 100 |
| er eval | luation. | 80 |
| | Cloar of loaks with | 60 |
| tion | Clear of leaks with 95% confidence level | 40 |
| | | 20 |
| | Survey | 0 |
| | map | |
| | | |
| | | Ack |
| | | This |
| | Possible | sub |
| | leaks present | Discla neces |
| nents p | roviding evidence to clear grid points. | Ref |
| ling evidence that grid points may contain leaks. | | Souz |
| | | |

Results to Date

- Method to estimate USR dimensions developed.
- Explainable and Auditable Statistical method to map and fuse USRs developed.
- Information flow clearly defined. Reproducible results.
- Framework evaluated with simulation tools (QUIC) and real UAV measurements.
- **Objective performance metrics (probability of finding leaks; size of clear region).**

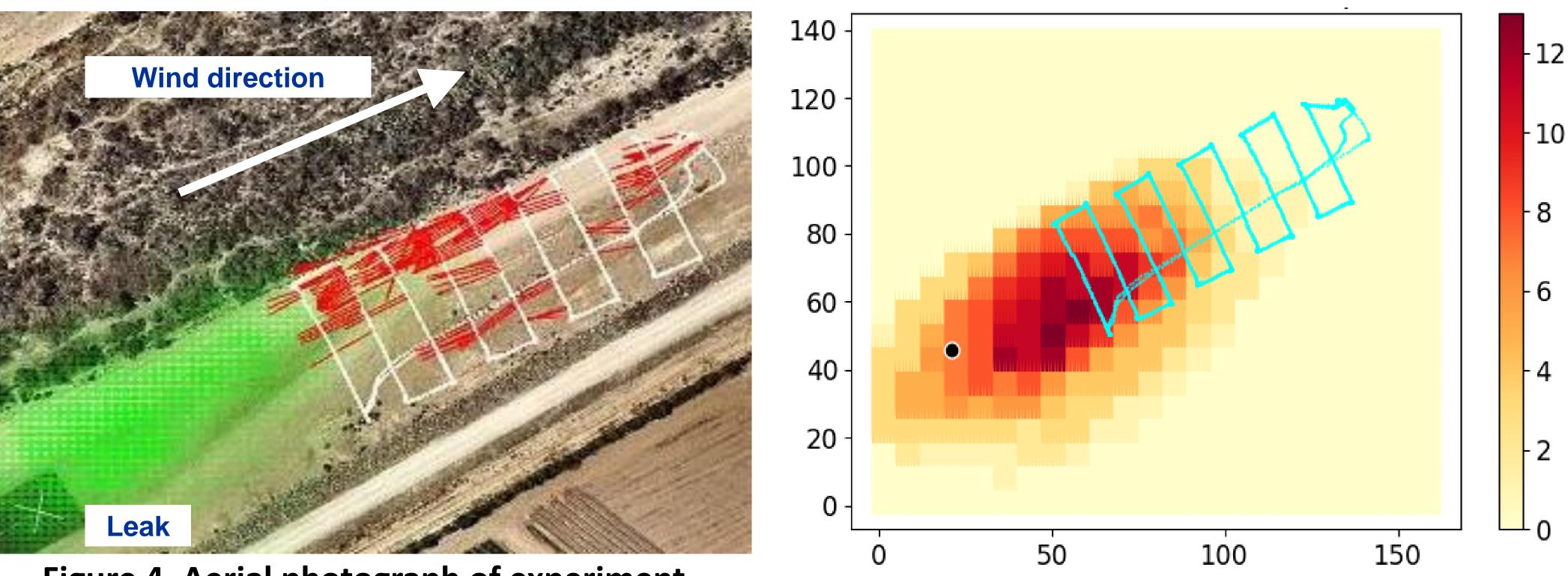
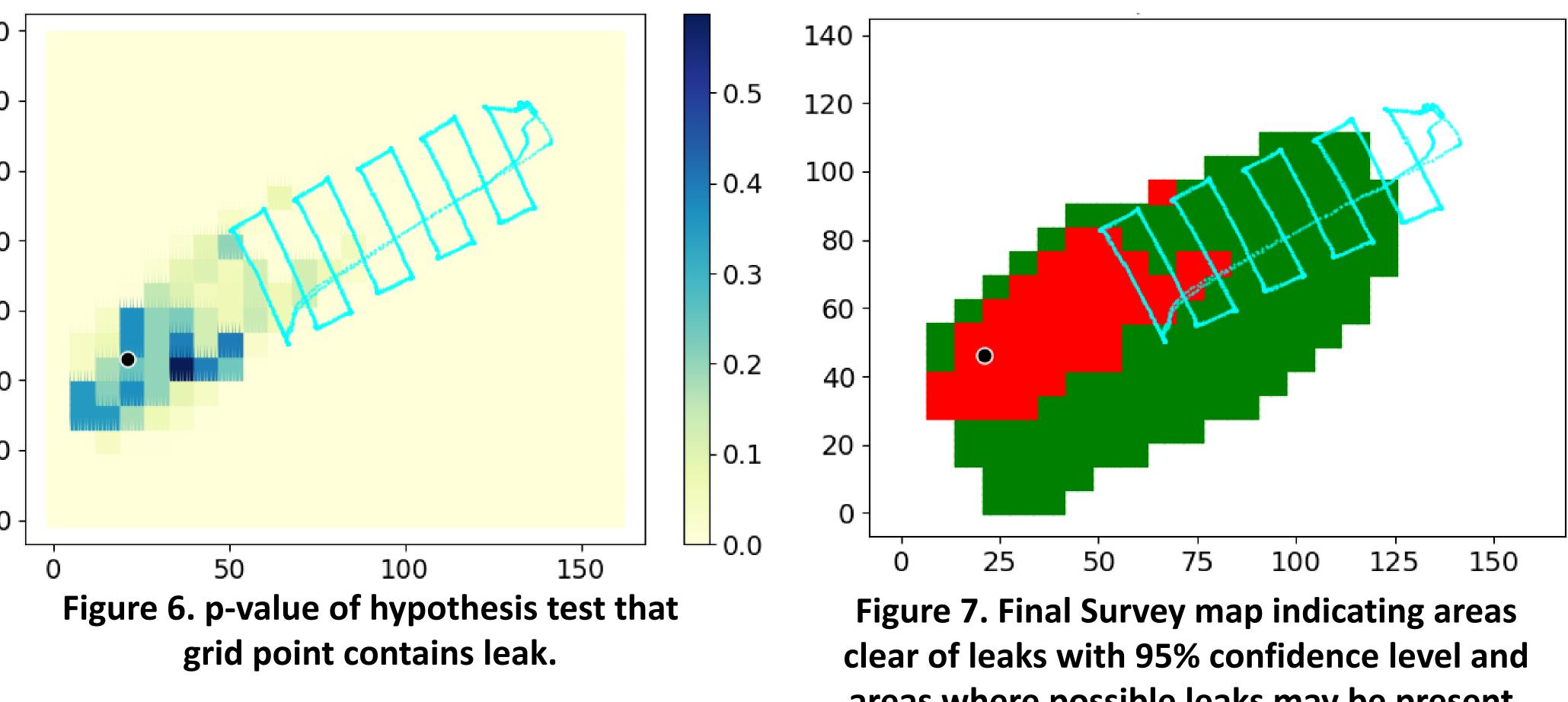


Figure 4. Aerial photograph of experiment. White lines indicate UAV path. **Red lines indicate detections by OPLS sensor.**



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laimer: Any opinions, findings, conclusions or recommendations expressed in this material are those of the authors and do not essarily reflect the views of NASA, Jet Propulsion Lab, or NYSearch.

ferences

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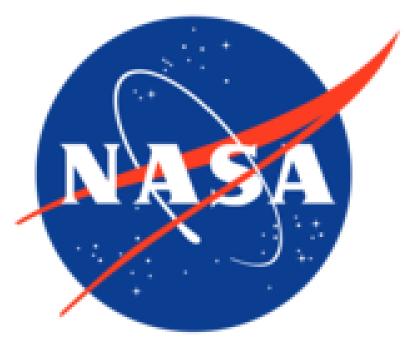


Figure 5. Number of USRs with high concentration covering each grid point.

areas where possible leaks may be present.